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Subir Kumar Ghosh



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Algorithms and Computation D. T. Lee, 2000 This book constitutes the refereed proceedings of the 11th International Conference on Algorithms and Computation ISAAC 2000 held in Taipei Taiwan in December 2000 The 46 revised papers presented together with an invited paper were carefully reviewed and selected from 87 submissions The papers are organized in topical sections on algorithms and data structures combinatorial optimization approximation and randomized algorithms graph drawing and graph algorithms automata cryptography and complexity theory parallel and distributed algorithms computational geometry and computational biology Automata, Languages and Programming Fernando Orejas, Paul G. Spirakis, Jan van Leeuwen, 2003-05-15 This book constitutes the refereed proceedings of the 28th International Colloquium on Automata Languages and Programming ICALP 2001 held in Crete Greece in July 2001 four invited papers were carefully reviewed and selected from a total of 208 submissions complexity algorithm analysis approximation and optimization complexity concurrency efficient data structures graph algorithms language theory codes and automata model checking and protocol analysis networks and routing reasoning and verification scheduling secure computation specification and deduction and structural complexity *Visibility Algorithms in the Plane* Subir Kumar Ghosh, 2007-03-29 A human observer can effortlessly identify visible portions of geometric objects present in the environment However computations of visible portions of objects from a viewpoint involving thousands of objects is a time consuming task even for high speed computers To solve such visibility problems efficient algorithms have been designed This book presents some of these visibility algorithms in two dimensions Specifically basic algorithms for point visibility weak visibility shortest paths visibility graphs link paths and visibility queries are all discussed Several geometric properties are also established through lemmas and theorems With over 300 figures and hundreds of exercises this book is ideal for graduate students and researchers in the field of computational geometry It will also be useful as a reference for researchers working in algorithms robotics computer graphics and geometric graph theory and some algorithms from the book can be used in a first course in computational geometry *Algorithms and Data Structures* Frank Dehne, 1997-07-23 The book is an introduction to the theory of cubic

metaplectic forms on the 3 dimensional hyperbolic space and the author s research on cubic metaplectic forms on special linear and symplectic groups of rank 2 The topics include Kubota and Bass Milnor Serre homomorphisms cubic metaplectic Eisenstein series cubic theta functions Whittaker functions A special method is developed and applied to find Fourier coefficients of the Eisenstein series and cubic theta functions The book is intended for readers with beginning graduate level background interested in further research in the theory of metaplectic forms and in possible applications Agents in Principle, Agents in Practice David Kinny,Jane Yung-jen Hsu,Guido Governatori,Aditya Ghose,2011-10-26 This book constitutes the proceedings of the 14th International Conference on Principles and Practice in Multi Agent Systems PRIMA 2011 held in Wollongong Australia in November 2011 The 39 papers presented together with 3 invited talks were carefully reviewed and selected from numerous submissions They focus on practical aspects of multiagent systems and are organised in topical sections on coalitions and teamwork learning mechanisms and voting modeling and simulation negotiation and coalitions optimization sustainability agent societies and frameworks argumentation and applications Index to IEEE Publications Institute of Electrical and Electronics Engineers,1997 **Intelligent Robots - Sensing, Modeling And Planning** Bob Bolles,Horst Bunke,Hartmut Noltemeier,1997-12-04 Rapid advances in sensors computers and algorithms continue to fuel dramatic improvements in intelligent robots In addition robot vehicles are starting to appear in a number of applications For example they have been installed in public settings to perform such tasks as delivering items in hospitals and cleaning floors in supermarkets recently two small robot vehicles were launched to explore Mars This book presents the latest advances in the principal fields that contribute to robotics It contains contributions written by leading experts addressing topics such as Path and Motion Planning Navigation and Sensing Vision and Object Recognition Environment Modeling and others *Cycle World Magazine* ,1997-01 Mathematics in Berlin Heinrich Begehr,Helmut Koch,Jürg Kramer,Norbert Schappacher,Ernst-Jochen Thiele,1998-07-21 This little book is conceived as a service to mathematicians attending the 1998 International Congress of Mathematicians in Berlin It presents a comprehensive condensed overview of mathematical activity in Berlin from Leibniz almost to the present day without however including biographies of living mathematicians Since many towering figures in mathematical history worked in Berlin most of the chapters of this book are concise biographies These are held together by a few survey articles presenting the overall development of entire periods of scientific life at Berlin Overlaps between various chapters and differences in style between the chapters were inevitable but sometimes this provided opportunities to show different aspects of a single historical event for instance the Kronecker Weierstrass controversy The book aims at readability rather than scholarly completeness There are no footnotes only references to the individual bibliographies of each chapter Still we do hope that the texts brought together here and written by the various authors for this volume constitute a solid introduction to the history of Berlin mathematics **Algorithmic Foundations of Robotics VI** Michael Erdmann,David Hsu,Mark Overmars,A. Frank van der Stappen,2005-06-23 Robot

algorithms are abstractions of computational processes that control or reason about motion and perception in the physical world. Because actions in the physical world are subject to physical laws and geometric constraints, the design and analysis of robot algorithms raise a unique combination of questions in control theory, computational and differential geometry, and computer science. Algorithms serve as a unifying theme in the multi-disciplinary field of robotics. This volume consists of selected contributions to the sixth Workshop on the Algorithmic Foundations of Robotics. This is a highly competitive meeting of experts in the field of algorithmic issues related to robotics and automation. Arts & Humanities Citation Index, 2001

Cumulated Index Medicus, 1997 **International Aerospace Abstracts**, 1997 **Single-Particle Structure of ^{29}Mg on the Approach to the $N = 20$ Island of Inversion** Patrick T. MacGregor, 2022-12-12 The nuclear shell model has had much success when describing nuclear structure. It is able to describe the single particle states of nuclei and gives understanding as to how nuclear structure evolves as the number of nucleons changes in a nucleus. This led to the discovery of the so-called magic numbers which designate particularly stable configurations of protons and neutrons in nuclei. With the advent of radioactive ion beams, it has become possible to probe exotic nuclei to test current theories of nuclear structure. These investigations have led to the discovery of exotic nuclear phenomena with structures different to those found in stable nuclei. One of these is the $N = 20$ island of inversion where configurations that appear in stable nuclei become less bound than more exotic particle-hole configurations across a shell gap. Another is the weakening of the magic $N = 20$ shell gap to $N = 16$ as the number of protons is reduced in this isotonic chain. Of particular interest are the magnesium isotopes which exhibit a swift transition into the island of inversion with ^{29}Mg lying outside and ^{31}Mg lying inside. In addition, ^{29}Mg lies one neutron outside $N = 16$ so is also able to give insight on the weakening of the $N = 16$ shell gap. Mapping this region of the chart of nuclides helps in the understanding of the evolution of this nuclear structure. A useful probe for this task is single particle transfer reactions. However, these reactions have been hindered by low yields from radioactive ion beams as well as suffering from kinematic effects that obscure the states that need to be observed. The ISOLDE Solenoidal Spectrometer (ISS) that measures these transfer reactions in a solenoidal magnetic field was designed to counteract these effects. With the high yield radioactive ion beams at ISOLDE, CERN, these transfer reactions became viable. Therefore, the nuclear structure of ^{29}Mg was probed using the $d + ^{28}\text{Mg} \rightarrow p + ^{29}\text{Mg}$ reaction using this device. This work marks the first measurement using the ISOLDE Solenoidal spectrometer and the first time that a solenoidal spectrometer has been used at an ISOL radioactive beam facility. The measurements highlight the interplay of nucleon-nucleon interactions and the geometry of the nuclear potential in driving observed trends in single particle structure, in particular the changes in closed shells towards doubly magic ^{24}O .

Handbook of Nuclear Physics Isao Tanihata, Hiroshi Toki, Toshitaka Kajino, 2023-09-04 This handbook is a comprehensive systematic source of modern nuclear physics. It aims to summarize experimental and theoretical discoveries and an understanding of unstable nuclei and their exotic structures which were opened up by the development of radioactive

ion RI beam in the late 1980s The handbook comprises three major parts In the first part the experiments and measured facts are well organized and reviewed The second part summarizes recognized theories to explain the experimental facts introduced in the first part Reflecting recent synergistic progress involving both experiment and theory the chapters both parts are mutually related The last part focuses on cosmo nuclear physics one of the mainstream subjects in modern nuclear physics Those comprehensive topics are presented concisely Supported by introductory reviews all chapters are designed to present their topics in a manner accessible to readers at the graduate level The book therefore serves as a valuable source for beginners as well helping them to learn modern nuclear physics

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