



Fig. 1877

Fig. 1877. Mechanism for motion regulation.

- 1. Slider block
- 2. Rotating arm
- 3. Guide rail
- 4. Pivoting point

The mechanism shown in Fig. 1877 is a simple mechanical linkage. It consists of a slider block (1) that moves along a guide rail (3). The slider block is connected to a rotating arm (2) by a vertical link. The rotating arm is pivoted at its other end to a fixed base (4). The motion of the slider block is converted into the rotational motion of the arm.

The mechanism shown in Fig. 1878 is a more complex mechanical linkage. It consists of a slider block (1) that moves along a guide rail (3). The slider block is connected to a rotating arm (2) by a vertical link. The rotating arm is pivoted at its other end to a fixed base (4). The motion of the slider block is converted into the rotational motion of the arm.

The mechanism shown in Fig. 1879 is a more complex mechanical linkage. It consists of a slider block (1) that moves along a guide rail (3). The slider block is connected to a rotating arm (2) by a vertical link. The rotating arm is pivoted at its other end to a fixed base (4). The motion of the slider block is converted into the rotational motion of the arm.

The mechanism shown in Fig. 1880 is a more complex mechanical linkage. It consists of a slider block (1) that moves along a guide rail (3). The slider block is connected to a rotating arm (2) by a vertical link. The rotating arm is pivoted at its other end to a fixed base (4). The motion of the slider block is converted into the rotational motion of the arm.

The mechanism shown in Fig. 1881 is a more complex mechanical linkage. It consists of a slider block (1) that moves along a guide rail (3). The slider block is connected to a rotating arm (2) by a vertical link. The rotating arm is pivoted at its other end to a fixed base (4). The motion of the slider block is converted into the rotational motion of the arm.

The mechanism shown in Fig. 1882 is a more complex mechanical linkage. It consists of a slider block (1) that moves along a guide rail (3). The slider block is connected to a rotating arm (2) by a vertical link. The rotating arm is pivoted at its other end to a fixed base (4). The motion of the slider block is converted into the rotational motion of the arm.

The mechanism shown in Fig. 1883 is a more complex mechanical linkage. It consists of a slider block (1) that moves along a guide rail (3). The slider block is connected to a rotating arm (2) by a vertical link. The rotating arm is pivoted at its other end to a fixed base (4). The motion of the slider block is converted into the rotational motion of the arm.

The mechanism shown in Fig. 1884 is a more complex mechanical linkage. It consists of a slider block (1) that moves along a guide rail (3). The slider block is connected to a rotating arm (2) by a vertical link. The rotating arm is pivoted at its other end to a fixed base (4). The motion of the slider block is converted into the rotational motion of the arm.

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