

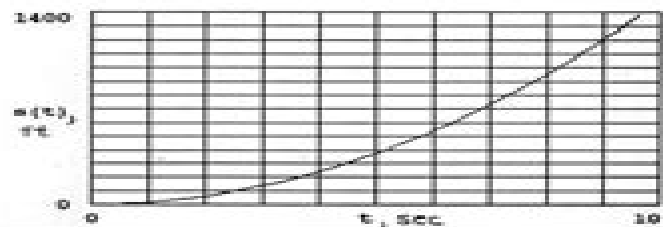
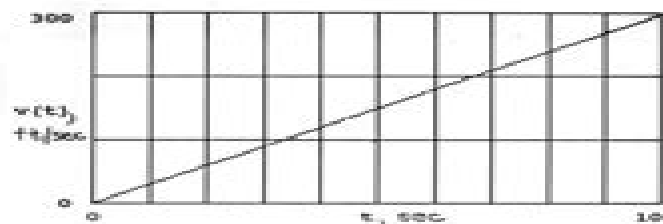
#2/253 $a = \frac{dv}{dt} = c_1 - c_2 v^2$
 $\int_0^t dt = \int_0^v \frac{dv}{c_1 - c_2 v^2} = \frac{1}{\sqrt{c_1 c_2}} \tanh^{-1} \sqrt{\frac{c_2}{c_1}} v \Big|_0^v$
 $t = \frac{1}{\sqrt{c_1 c_2}} \tanh^{-1} \sqrt{\frac{c_2}{c_1}} v$

Then $v = \frac{ds}{dt} = \sqrt{\frac{c_1}{c_2}} \tanh \sqrt{c_1 c_2} t$
 $\int ds = \sqrt{\frac{c_1}{c_2}} \int_0^t \tanh \sqrt{c_1 c_2} t dt$
 $s = \sqrt{\frac{c_1}{c_2}} \cdot \frac{1}{\sqrt{c_1 c_2}} \ln (\cosh \sqrt{c_1 c_2} t) \Big|_0^t$
 $= \frac{1}{c_2} \ln (\cosh \sqrt{c_1 c_2} t)$

With $s = 1320$ ft, $c_1 = 30$ ft/sec², $t = 9.4$ sec:
 $1320 = \frac{1}{c_2} \ln (\cosh \sqrt{30 c_2} \cdot 9.4)$
 $= \frac{1}{c_2} \ln (\cosh 51.5 \sqrt{c_2})$

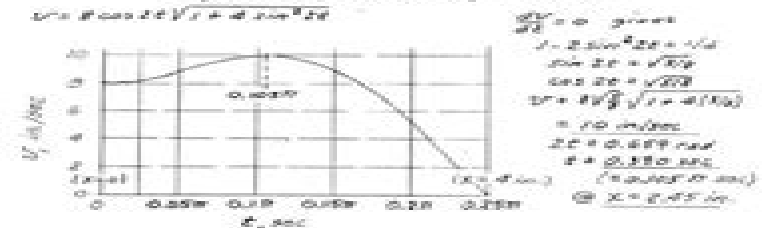
Numerical solution: $c_2 = 9.28 \text{ (s}^{-1}\text{)} \text{ ft}^{-1}$

(On plots below, note that v vs. t appears linear, but it is not!)



#2/254 $a = v \frac{dv}{dy} = -g - kv^2$
 $\int_{v_0}^0 \frac{v dv}{-g - kv^2} = \int_0^h dy$
Let $u = g + kv^2$, $du = 2kv dv$: $\int_{v_0}^0 -\frac{1}{2k} \frac{du}{u} = h$
 $h = -\frac{1}{2k} \ln (g + kv^2) \Big|_{v_0}^0 = -\frac{1}{2k} \ln \left(\frac{g}{g + kv_0^2} \right)$
 $2kh = \ln \left(1 + \frac{kv_0^2}{g} \right) : 2(528)(k)(8) = \ln \left(1 + \frac{2 \cosh^2 k}{32.2} \right)$
Solve numerically to obtain $k = 3.63 \text{ (s}^{-1}\text{)} \text{ ft}^{-1}$

#2/255 $y = x^2/8$, x & y in inches; $x = 4 \sin 2t$, t in seconds
 $\dot{y} = \frac{dy}{dt} = 2 \sin 2t (2 \cos 2t) = 4 \sin 2t \cos 2t$ in./sec
 $\dot{x} = 8 \cos 2t$
 $v^2 = \dot{x}^2 + \dot{y}^2 = 64 \cos^2 2t + 16 \sin^2 2t \cos^2 2t$
 $= 16 \cos^2 2t (1 + 4 \sin^2 2t)$ (in./sec)²
 $v = 4 \cos 2t \sqrt{1 + 4 \sin^2 2t}$



#2/258 Set up x-y coordinates @ A: $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} R \\ h \end{pmatrix}$
Let coordinates of B be (R, h) .
 $x = x_0 + v_{x0} t$ @ B: $R = 0 + (v_0 \cos \alpha) t$ (1)
 $y = y_0 + v_{y0} t - \frac{1}{2} g t^2$ @ B: $h = 0 + (v_0 \sin \alpha) t - \frac{1}{2} g t^2$ (2)
Solve (1) & (2) for R & t :
 $R = \frac{v_0 \cos \alpha}{g} \left[v_0 \sin \alpha + \sqrt{v_0^2 \sin^2 \alpha - 2gh} \right]$
 $t = \frac{1}{g} \left[v_0 \sin \alpha + \sqrt{v_0^2 \sin^2 \alpha - 2gh} \right]$
where the + sign has been taken to maximize R .
Set $\frac{dR}{d\alpha} = 0$ (done by computer) to find
 $\alpha = 48.5^\circ$ (for $h = 10$ m, $v_0 = 30$ m/s, and $g = 9.81$ m/s²)

The corresponding value of R is

$R = 81.1$ m

So the 10-m plateau is indeed achieved, as assumed (because $R > 50$ m).

Solution For Meriam Dynamics

James L. Meriam



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700 Solved Problems In Vector Mechanics for Engineers: Dynamics Joseph F. Shelley, 1991-04 Suitable for 2nd year college and university engineering students this book provides them with a source of problems with solutions in vector mechanics that covers various aspects of the basic course It offers the comprehensive solved problem reference in the subject It also provides the student with the problem solving drill

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Engineering Mechanics: Dynamics James L. Meriam, 2002

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Engineering Mechanics, Dynamics, Study Guide J. L. Meriam, L. G. Kraige, 1997-03-21 This concise and authoritative book emphasizes basic principles and problem formulation It illustrates both the cohesiveness of the relatively few fundamental ideas in this area and the great variety of problems these ideas solve All of the problems address principles and procedures inherent in the design and analysis of engineering structures and mechanical systems with many of the problems referring explicitly to design considerations

Applied Mechanics Reviews, 1972

Study Guide to Accompany Engineering Mechanics: Dynamics James L. Meriam, 1997

Dynamics James L. Meriam, 1959

Nonlinear Structural Dynamics Using FE Methods James F. Doyle, 2014-10-06 This book will be useful to students and practicing engineers giving them a richer understanding of their trade and accelerating learning on new problems Independent workers will find access to advanced topics presented in an accessible manner

Mechanical Vibration Haym Benaroya, 2004-10-13 An effective text must be well balanced and thorough in its approach to a topic as expansive as vibration and Mechanical Vibration is just such a textbook Written for both senior undergraduate and graduate course levels this updated and expanded second edition integrates uncertainty and control into the discussion of vibration outlining basic concepts before delving into the mathematical rigors of modeling and analysis Mechanical Vibration Analysis Uncertainties and Control Second Edition provides example problems end of chapter exercises and an up to date set of mini projects to enhance students computational abilities and includes abundant references for further study or more in depth information The author provides a MATLAB primer on an accompanying CD ROM which contains original programs that can be used to solve complex

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Engineering Mechanics Millard F. Beatty Jr., 2013-12-18 Separation of the elements of classical mechanics into kinematics and dynamics is an uncommon tutorial approach but the author uses it to advantage in this two volume set Students gain a mastery of kinematics first a solid foundation for the later study of the free body formulation of the dynamics problem A key objective of these volumes which present a vector treatment of the principles of mechanics is to help the student gain confidence in transforming problems into appropriate mathematical language that may be manipulated to give useful physical conclusions or specific numerical results In the first volume the elements of vector calculus and the matrix algebra are reviewed in appendices Unusual mathematical topics such as singularity functions and some elements of tensor analysis

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