

Chapter 2

Calculus of Variations and Optimal Control

Solution to Problem 2.1

The performance index is

$$\begin{aligned} J &= \int_0^2 [2x^2(t) + \dot{x}^2(t)] dt, \\ &= \int_{t_0}^{t_f} V(x(t), \dot{x}(t)) dt \end{aligned}$$

where

$$V = 2x^2(t) + \dot{x}^2(t), \quad t_0 = 0, \quad t_f = 2.$$

Using the Euler-Lagrange equation (2.3.15)

$$\begin{aligned} \left(\frac{\partial V}{\partial x} \right)_* - \frac{d}{dt} \left(\frac{\partial V}{\partial \dot{x}} \right)_* &= 0 \longrightarrow \\ 4x^*(t) - \frac{d}{dt} (2\dot{x}^*(t)) &= 0 \longrightarrow \\ \ddot{x}^*(t) - 2x^*(t) &= 0. \end{aligned}$$

Solving the previous equation

$$x^*(t) = C_1 e^{\sqrt{2}t} + C_2 e^{-\sqrt{2}t}$$

Optimal Control Systems Problems And Solutions Manual

Wayne D. Gray



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Optimal Control Brian D. O. Anderson, John B. Moore, 2007-02-27 Numerous examples highlight this treatment of the use of linear quadratic Gaussian methods for control system design It explores linear optimal control theory from an engineering viewpoint with illustrations of practical applications Key topics include loop recovery techniques frequency shaping and controller reduction Numerous examples and complete solutions 1990 edition **Resilient Control Architectures and**

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Scientific and Technical Aerospace Reports ,1993 **Applied Mechanics Reviews** ,1974 Modern Control Engineering Katsuhiko Ogata, 1997 Comprehensive treatment of the analysis and design of continuous time control systems Partial contents The Laplace transform Mathematical modelling of dynamic system Transient response analysis Root locus analysis Frequency response analysis PID controls and introduction to robust control Control systems in state space Liapunov stability analysis and quadratic optimal control **Modern Control Engineering** P.N. Paraskevopoulos, 2017-12-19 Illustrates the analysis behavior and design of linear control systems using classical modern and advanced control techniques Covers recent methods in system identification and optimal digital adaptive robust and fuzzy control as well as stability

controllability observability pole placement state observers input output decoupling and model matching Integrated Models of Cognitive Systems Wayne D. Gray, 2007-04-19 The field of cognitive modeling has progressed beyond modeling cognition in the context of simple laboratory tasks and begun to attack the problem of modeling it in more complex realistic environments such as those studied by researchers in the field of human factors The problems that the cognitive modeling community is tackling focus on modeling certain problems of communication and control that arise when integrating with the external environment factors such as implicit and explicit knowledge emotion cognition and the cognitive system These problems must be solved in order to produce integrated cognitive models of moderately complex tasks Architectures of cognition in these tasks focus on the control of a central system which includes control of the central processor itself initiation of functional processes such as visual search and memory retrieval and harvesting the results of these functional processes Because the control of the central system is conceptually different from the internal control required by individual functional processes a complete architecture of cognition must incorporate two types of theories of control Type 1 theories of the structure functionality and operation of the controller and type 2 theories of the internal control of functional processes including how and what they communicate to the controller This book presents the current state of the art for both types of theories as well as contrasts among current approaches to human performance models It will be an important resource for professional and student researchers in cognitive science cognitive engineering and human factors Contributors Kevin A Gluck Jerry T Ball Michael A Krusmark Richard W Pew Chris R Sims Vladislav D Veksler John R Anderson Ron Sun Nicholas L Cassimatis Randy J Brou Andrew D Egerton Stephanie M Doane Christopher W Myers Hansj rg Neth Jeremy M Wolfe Marc Pomplun Ronald A Rensink Hansj rg Neth Chris R Sims Peter M Todd Lael J Schooler Wai Tat Fu Michael C Mozer Sachiko Kinoshita Michael Shettel Alex Kirlik Vladislav D Veksler Michael J Schoelles Jerome R Busemeyer Eric Dimperio Ryan K Jessup Jonathan Gratch Stacy Marsella Glenn Gunzelmann Kevin A Gluck Scott Price Hans P A Van Dongen David F Dinges Frank E Ritter Andrew L Reifers Laura Cousino Klein Michael J Schoelles Eva Hudlicka Hansj rg Neth Christopher W Myers Dana Ballard Nathan Sprague Laurence T Maloney Julia Trommersh user Michael S Landy A Hornof Michael J Schoelles David Kieras Dario D Salvucci Niels Taatgen Erik M Altmann Richard A Carlson Andrew Howes Richard L Lewis Alonso Vera Richard P Cooper and Michael D Byrne Robotics, CAD/CAM Market Place, 1985 ,1985 **Research and Technology Program Digest** United States. National Aeronautics and Space Administration, *U.S. Government Research & Development Reports* ,1967 **Bulletin of the Society for the Promotion of Engineering Education** ,1969 *Modern Control System Theory and Design* Stanley M. Shinnars, 1998-05-06 The definitive guide to control system design *Modern Control System Theory and Design* Second Edition offers the most comprehensive treatment of control systems available today Its unique text software combination integrates classical and modern control system theories while promoting an interactive computer based approach to design solutions The sheer volume of practical examples as well as the hundreds of

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