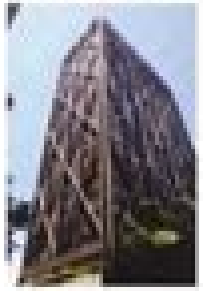
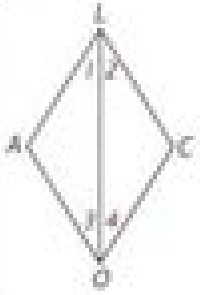
Alcoa Building. The architects who designed the Alcoa building in San Francisco used a grid of isosceles triangles.*



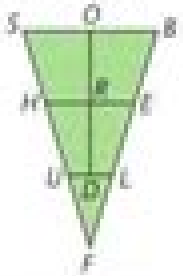


16. Copy this figure based on that grid and mark the following information on it: AL = LC = CO = OA; ∠A = ∠C.
17. What kind of triangles are △LAO and △LCO?
18. Why is ∠1 = ∠3 and ∠2 = ∠4?
19. Why is ∠1 + ∠2 = ∠3 + ∠4?

From the figure, we see that LA·LO·LC and OA·OL·OC.

20. Why is ∠ALC = ∠1 + ∠3 and ∠AOC = ∠3 + ∠4?
21. Why is ∠ALC = ∠AOC?
22. Why is △LAO ≅ △LCO?
23. Why is ∠1 = ∠3 and ∠3 = ∠4?
24. What relation does LO have to ∠ALC and ∠AOC?

Shuffleboard Court. The figure at the right shows one of the scoring zones of a shuffleboard court. SH = HU = UF = FL = LE = ES.



*Geometry in Architecture, by William Blackwell (Wiley, 1984).

25. What relation does OD appear to have to SB, HE, and UL?
26. What relation do SB, HE, and UL appear to have to one another?
27. What kind of triangles are △SBF, △HED, and △ULF?

Given that ∠F = 36°, find the measures of

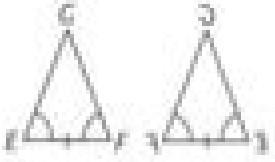
28. ∠5 and ∠8.
29. ∠LUF and ∠ULF.
30. ∠SLS and ∠BLU.

Set II

Theorem 10 can be proved in a way almost identical with the proof of Theorem 9.

31. Write a complete proof of Theorem 10 by first copying it, the figure, and the "given" and "prove." Use the proof of Theorem 9 as a guide in writing your proof.

Theorem 10. If two angles of a triangle are equal, the sides opposite them are equal.



Given: In △EFG, ∠E = ∠F.
Prove: GE = GF.

Theorem 9 can be used to prove its corollary.

32. Write a complete proof of the corollary by first copying it, the figure, and the "given" and "prove." Copy the statements and give the reasons.

Corollary. An equilateral triangle is equiangular.

Given: △ABC is equilateral.
Prove: △ABC is equiangular.

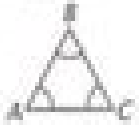
Proof

Statements	*Reasons*
1. △ABC is equilateral.	Why?
2. BC = AC and AC = AB.	Why?
3. ∠A = ∠B and ∠B = ∠C.	Why?
4. ∠A = ∠C.	Why?
5. △ABC is equiangular.	Why?

The proof of the corollary to Theorem 10 is almost the same.

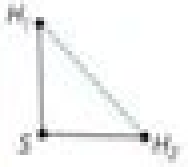
33. Copy the following and use the proof to exercise 31 as a guide in writing your proof.

Corollary. An equiangular triangle is equilateral.



Given: △ABC is equiangular.
Prove: △ABC is equilateral.

Hydrogen Sulfide. One of the reasons that rotten eggs stink is hydrogen sulfide. The hydrogen sulfide molecule consists of a sulfur atom bonded to two hydrogen atoms.*



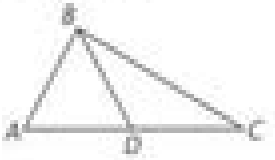
In △SH_1H_2, S represents the center of the sulfur atom; H_1 and H_2 represents the centers of the hydrogen atoms; $SH_1 = SH_2$.

34. What kind of triangle is △SH_1H_2 with respect to its sides?

The measure of ∠H_1 is 45.9°. Find the measure of

35. ∠H_2.
36. ∠S.
37. What kind of triangle is △SH_1H_2 with respect to its angles?
38. If you know that $SH_1 = SH_2 = 1.34$ angstroms, could you use the Pythagorean Theorem to find the length of H_1H_2? Explain.

In the figure below, △ABD is equiangular and D is the midpoint of AC.

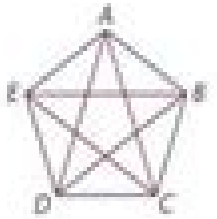


39. Copy the figure and mark this information on it.

△BDC is evidently obtuse.

40. What further conclusions can you draw about △BDC? Explain your reasoning.

Star Puzzle. In the accurately drawn figure below, 10 line segments connect the 5 lettered points.



41. What kind of polygon is the blue polygon?
42. Why isn't the red star a polygon?

All of the sides and angles of the blue polygon are equal.

43. Do you think that the 5 line segments that form the red star also must be equal? Explain why or why not.

*The Architecture of Molecules, by Linus Pauling and Roger Hayward (W. H. Freeman and Company, 1964).

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G. Farin,J. Hoschek,M.-S. Kim

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Prentice Hall Informal Geometry Philip L. Cox,1992 *Handbook of Computer Aided Geometric Design* G. Farin,J. Hoschek,M.-S. Kim,2002-08-13 This book provides a comprehensive coverage of the fields Geometric Modeling Computer Aided Design and Scientific Visualization or Computer Aided Geometric Design Leading international experts have contributed thus creating a one of a kind collection of authoritative articles There are chapters outlining basic theory in tutorial style as well as application oriented articles Aspects which are covered include Historical outline Curve and surface methods Scientific Visualization Implicit methods Reverse engineering This book is meant to be a reference text for researchers in the field as well as an introduction to graduate students wishing to get some exposureto this subject **The Mechanics of Robot Grasping** Elon Rimon,Joel Burdick,2019-10-24 This comprehensive look at the major concepts in robot grasp mechanics serves as a valuable reference for all robotics enthusiasts **Algorithmic Topology and Classification of 3-Manifolds** Sergei Matveev,2013-04-17 The book is devoted to algorithmic low dimensional topology This branch of mathematics has recently been undergoing an intense development On the one hand the exponential advancement of computer technologies has made it possible to conduct sophisticated computer experiments and to implement algorithmic solutions which have in turn provided a motivation to search for new and better algorithms On the other hand low dimensional topology has received an additional boost because of the discovery of numerous connections with theoretical physics There is also another deep reason why algorithmic topology has received a lot of attention It is that a search for algorithmic solutions generally proves to be a rich source of well stated mathematical problems Speaking out of my experience it seems that an orientation towards how to rather than just how is serves as a probing stone for choosing among possible directions of research much like problems in mechanics led once to the development of calculus **Structural Dynamic Systems Com** Cornelius T. Leondes,1999-01-27 The availability of powerful computers along with highly effective computational techniques have allowed computer aided design and engineering of structural dynamics systems to achieve a high level of capability and importance This volume clearly reveals the great significance of these techniques and the essential role they will play in the future as further development occurs This will be a significant and unique reference for students research workers practitioners computer scientists and others for years to come **Handbook of Research for Educational Communications and Technology** David Jonassen,Marcy Driscoll,2003-12-08 First Published in 2008 Routledge is an imprint of Taylor Francis an informa company The School Journal ,1898 *Graph Drawing Software* Michael Jünger,Petra Mutzel,2012-12-06 Automatic Graph Drawing is concerned with the layout of relational structures as they occur in Computer Science Data Base Design Data Mining Web Mining Bioinformatics Metabolic Networks Businessinformatics Organization Diagrams Event Driven Process Chains or the Social Sciences Social Networks In mathematical terms such relational structures are modeled as graphs or more general objects such as hypergraphs clustered

graphs or compound graphs A variety of layout algorithms that are based on graph theoretical foundations have been developed in the last two decades and implemented in software systems After an introduction to the subject area and a concise treatment of the technical foundations for the subsequent chapters this book features 14 chapters on state of the art graph drawing software systems ranging from general tool boxes to customized software for various applications These chapters are written by leading experts they follow a uniform scheme and can be read independently from each other

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edition of the papers selected from the 13 International Conference on Advanced Robotics ICAR 2007 held in Jeju Korea August 22 25 2007 with the theme Viable Robotics Service to Human It is intended to deliver readers the most recent technical progress in robotics in particular toward the advancement of robotic service to human To ensure its quality this volume took only 28 papers out of the 214 papers accepted for publication for ICAR 2007 The selection was based mainly on the technical merit but also took into consideration whether the subject represents a theme of current interest For the final inclusion authors of the selected papers were requested for another round of revision and expansion In this volume we organize the 28 contributions into three chapters Chapter 1 covers Novel Mechanisms Chapter 2 deals with perception guided navigation and manipulation and Chapter 3 addresses human robot interaction and intelligence Chapters 1 2 and 3 consist of 7 13 and 8 contributions respectively For the sake of clarity Chapter 2 is divided further into two parts with Part 1 for Perception Guided Navigation and Part 2 for Perception Guided Manipulation Chapter 3 is also divided into two parts with Part 1 for Human Robot Interaction and Part 2 for Intelligence For the convenience of readers a ch ter summary is introduced as an overview in the beginning of each chapter The chapter summaries were prepared by Dr Munsang Kim for Chapter 1 Prof Handbook of Research on Advanced Applications of Graph Theory in Modern Society Pal, Madhumangal,Samanta, Sovan,Pal, Anita,2019-08-30 In the world of mathematics and computer science technological advancements are constantly being researched and applied to ongoing issues Setbacks in social networking engineering and automation are themes that affect everyday life and researchers have been looking for new techniques in which to solve these challenges Graph theory is a widely studied topic that is now being applied to real life problems The Handbook of Research on Advanced Applications of Graph Theory in Modern Society is an essential reference source that discusses recent developments on graph theory as well as its representation in social networks artificial neural networks and many complex networks The book aims to study results that are useful in the fields of robotics and machine learning and will examine different engineering issues that are closely related to fuzzy graph theory Featuring research on topics such as artificial neural systems and robotics this book is ideally designed for mathematicians research scholars practitioners professionals engineers and students seeking an innovative overview of graphic theory *Graph Algorithms and Applications 2* Giuseppe Liotta,Roberto Tamassia,Ioannis G. Tollis,2004 This book contains Volumes 4 and 5 of the Journal of Graph Algorithms and Applications JGAA The first book of this series Graph Algorithms and Applications 1 published in March 2002 contains Volumes 1OCo3 of JGAA JGAA is a peer reviewed scientific journal devoted to the publication of high quality research papers on the analysis design implementation and applications of graph algorithms Areas of interest include computational biology computational geometry computer graphics computer aided design computer and interconnection networks constraint systems databases graph drawing graph embedding and layout knowledge representation multimedia software engineering telecommunications networks user interfaces and visualization and VLSI circuit design The journal is supported by

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