

CHAPTER 3

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B-3-1. $J = \frac{1}{2} mR^2 = \frac{1}{2} \times 100 \times 0.5^2 = 12.5 \text{ kg-m}^2$

B-3-2. Assume that the body of known moment of inertia J_0 is turned through a small angle θ about the vertical axis and then released. The equation of motion for the oscillation is

$$J_0 \ddot{\theta} = -k\theta$$

where k is the torsional spring constant of the string. This equation can be written as

$$\ddot{\theta} + \frac{k}{J_0} \theta = 0$$

or

$$\ddot{\theta} + \omega_n^2 \theta = 0$$

where

$$\omega_n = \sqrt{\frac{k}{J_0}}$$

The period T_0 of this oscillation is

$$T_0 = \frac{2\pi}{\omega_n} = \frac{2\pi}{\sqrt{\frac{k}{J_0}}} \quad (1)$$

Next, we attach a rotating body of unknown moment of inertia J and measure the period T of oscillation. The equation for the period T is

$$T = \frac{2\pi}{\sqrt{\frac{k}{J}}} \quad (2)$$

By eliminating the unknown torsional spring constant k from Equations (1) and (2), we obtain

$$\frac{2\pi\sqrt{J_0}}{T_0} = \frac{2\pi\sqrt{J}}{T}$$

Hence

$$J = J_0 \left(\frac{T}{T_0} \right)^2 \quad (3)$$

The unknown moment of inertia J can therefore be determined by measuring the period of oscillation T and substituting it into Equation (3).

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Theory of Vibration Protection Igor A. Karnovsky, Evgeniy Lebed, 2016-05-09 This text is an advancement of the theory of vibration protection of mechanical systems with lumped and distributed parameters The book offers various concepts and methods of solving vibration protection problems discusses the advantages and disadvantages of different methods and the fields of their effective applications Fundamental approaches of vibration protection which are considered in this book are the passive parametric and optimal active vibration protection The passive vibration protection is based on vibration isolation vibration damping and dynamic absorbers Parametric vibration protection theory is based on the Shchipanov Luzin invariance principle Optimal active vibration protection theory is based on the Pontryagin principle and the Krein moment method The book also contains special topics such as suppression of vibrations at the source of their occurrence and the harmful influence of vibrations on humans p Numerous examples which illustrate the theoretical ideas of each chapter are included This book is intended for graduate students and engineers It is assumed that a reader has working knowledge of theory of vibrations differential equations and complex analysis About the Authors Igor A Karnovsky Ph D Dr Sci is a specialist in structural analysis theory of vibration and optimal control of vibration He has 40 years of experience in research teaching and consulting in this field and is the author of more than 70 published scientific papers including two books in Structural Analysis published with Springer in 2010 2012 and three handbooks in Structural Dynamics published with McGraw Hill in 2001 2004 He also holds a number of vibration control related patents Evgeniy Lebed Ph D is a specialist in applied mathematics and engineering He has 10 years of experience in research teaching and consulting in this field The main sphere of his research interests are qualitative theory of differential equations integral transforms and frequency domain analysis with application to image and signal processing He is the author of 15 published scientific papers and a US patent 2015 Modeling of Dynamic Systems with Engineering Applications Clarence W. de Silva, 2022-07-27 This book provides cutting edge insight into systems dynamics for both students and practicing engineers Updated throughout for the second edition this book serves as a firm foundation to develop expertise in design prototyping control instrumentation experimentation and performance analysis Providing a clear discussion of system dynamics this book enables students and professionals to both understand and subsequently model mechanical thermal fluid electrical and multi domain or multi physics systems in a systematic unified and integrated manner Concepts of through and across variables are introduced and applied alongside tools of modeling and model representation in linear graphs This book uses innovative worked examples and case studies alongside problems and exercises based on practical situations This book is a crucial companion to undergraduate and postgraduate engineering students alongside professionals in the engineering field Complete solutions to end of chapter problems are provided in a solutions manual which is available to instructors **Engineering System Dynamics** Forbes T. Brown, 2006-08-15 For today s students learning to model the dynamics of complex systems is

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used in a mercury pressure gauge The inner diameter of the tube is 8 0 mm **Solutions Manual, Modeling and Analysis of Dynamic Systems, Second Edition** Charles M. Close, Dean K. Frederick, 1993-01-01 Engineering Education ,1977

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the mechanical aspects of vehicles emphasizing steering handling ride and related components

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