


3/1 $v_2^2 - v_1^2 = 2a(x_2 - x_1)$
 $0^2 - \left(\frac{100}{3.2}\right)^2 = 2a_x(50)$, $a_x = -7.72 \text{ m/s}^2$


$\Sigma F_x = ma_x$: $-4F = 1500(-7.72)$
 $F = 2870 \text{ N}$

3/2 $50(9.81) \text{ N}$ $\Sigma F_y = 0$: $N - 50(9.81) \cos 15^\circ = 0$
 $N = 474 \text{ N}$ Throughout

(a) $P = 0$
 Equilibrium check:
 $\Sigma F_x = 0$: $F - 50(9.81) \sin 15^\circ = 0$
 $F = 127.9 \text{ N}$

$F_{\max} = \mu_s N = 0.2(474) = 94.8 \text{ N} < F$: motion \checkmark
 $\Sigma F_x = ma_x$: $0.15(474) - 50(9.81) \sin 15^\circ = 50a_x$
 $a_x = -1.118 \text{ m/s}^2$

(b) $P = 150 \text{ N}$; Equilibrium check:
 $\Sigma F_y = 0$: $150 + F - 50(9.81) \sin 15^\circ = 0$


$F = -23.9 \text{ N}$, $|F| < F_{\max}$ so no motion: $a = 0$


(c) $P = 300 \text{ N}$; Equilibrium check yields $F = -173.0 \text{ N}$
 $|F| > F_{\max}$, so motion \checkmark , $F = F_k \checkmark$
 $\Sigma F_x = ma_x$: $300 - 0.15(474) - 50(9.81) \sin 15^\circ = 50a_x$
 $a_x = 2.04 \text{ m/s}^2$


3/3 80 lb $\Sigma F_y = 0$: $N - 80 \cos 20^\circ = 0$
 $N = 75.2 \text{ lb}$
 $\Sigma F_x = ma_x$:
 $-0.25(75.2) - 80 \sin 20^\circ = \frac{80}{32.2} a$
 $a = -18.58 \text{ ft/sec}^2$


$v = v_0 + at$: $0 = 30 - 18.58t$, $t = 1.615 \text{ sec}$
 $v^2 = v_0^2 + 2a(s - s_0)$: $0^2 = 30^2 + 2(-18.58)d$
 $d = 24.2 \text{ ft}$

$v^2 = v_0^2 + 2a(s - s_0)$: $15^2 = 30^2 + 2(-18.58)d'$
 $d' = 18.17 \text{ ft}$

3/4 $300,000(9.81) \text{ N}$

 $\Sigma F_x = ma_x$:
 $3(240,000) - 300,000(9.81) \sin \frac{1}{2}^\circ = 300,000 a_x$
 $a_x = 2.31 \text{ m/s}^2$
 $v^2 = 2a_x s$: $\left(\frac{220}{3.6}\right)^2 = 2(2.31)s$, $s_x = 807 \text{ m}$

$300,000(9.81) \text{ N}$

 $\Sigma F_x = ma_x$:
 $3(240,000) + 300,000(9.81) \sin \frac{1}{2}^\circ = 300,000 a_x$
 $a_x = 2.49 \text{ m/s}^2$
 $v^2 = 2a_x s$: $\left(\frac{220}{3.6}\right)^2 = 2(2.49)s$, $s_x = 751 \text{ m}$

3/5 For entire unit: $20,000 \text{ kg}$ $10,000 \text{ kg}$
 $\Sigma F = ma$: $20,000 = 30,000a$
 $a = 0.667 \text{ m/s}^2$
 For trailer alone, $T = 20,000(0.667) = 13,330 \text{ N}$
 or $T = 13.33 \text{ kN}$


3/6 $\Sigma F_x = ma_x$: $mg \sin 40^\circ - \mu_k mg \cos 40^\circ = ma$
 $a = 9.81(\sin 40^\circ - \mu_k \cos 40^\circ)$
 $= 6.31 - 7.51 \mu_k$


For constant accel. $s = v_0 t + \frac{1}{2}at^2$:
 $20 = 0 + \frac{1}{2}(6.31 - 7.51 \mu_k)2.58^2$
 $\mu_k = 0.0595$

3/7 $\Sigma F = ma$: $T - 100 = \frac{100}{32.2} a$
 (a) $T \uparrow$  $150 - T = \frac{150}{32.2} a$
 $50 = \frac{250}{32.2} a$, $a = \frac{32.2}{5} = 6.44 \frac{\text{ft}}{\text{sec}^2}$
 (b)  $150 - 100 = \frac{100}{32.2} a$, $a = \frac{32.2}{2} = 16.10 \frac{\text{ft}}{\text{sec}^2}$

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James L. Meriam, L. Glenn Kraige



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Engineering Mechanics James L. Meriam, L. G. Kraige, 2012-03-19 The 7th edition continues to provide the same high quality material seen in previous editions. It provides extensively rewritten updated prose for content clarity, superb new problems in new application areas, outstanding instruction on drawing free body diagrams, and new electronic supplements to assist learning and instruction.

Meriam's Engineering Mechanics James L. Meriam, L. Glenn Kraige, J. N. Bolton, L. G. Kraige, 2020-03-17 Known for its accuracy, clarity, and dependability, Meriam, Kraige, and Bolton's *Engineering Mechanics: Statics*, 9th Edition, has provided a solid foundation of mechanics principles for more than 60 years. This text continues to help students develop their problem-solving skills with an extensive variety of engaging problems related to engineering design. In addition to new homework problems, the text includes a number of helpful sample problems. To help students build necessary visualization and problem-solving skills, the text strongly emphasizes drawing free body diagrams, one of the most important skills needed to solve mechanics problems.

Engineering Dynamics Oliver M. O'Reilly, 2013-03-09 Scope, Aims, and Audiences. This primer is intended to provide the theoretical background for the standard undergraduate course in dynamics. This course is usually based on one of the following texts: Bedford and Fowler, Beer and Johnston, Hibbeler, Meriam and Kraige, Riley and Sturges, and Shames, among others. Although most teachers will have certain reservations about these texts, there appears to be a general consensus that the selection of problems each of them presents is an invaluable and essential aid for studying and understanding dynamics. I myself use Meriam and Kraige 39 when teaching such a course, which is referred to as ME104 at the University of California at Berkeley. However, I have found that the gap between the theory presented in the aforementioned texts and the problems I wished my students to solve was too large. As a result, I prepared my own set of notes on the relevant theory, and I used Meriam and Kraige 39 as a problem and homework resource. This primer grew out of these notes. Its content was also heavily influenced by three other courses that I teach: one on rigid body dynamics, one on Lagrangian mechanics, and another on Hamiltonian mechanics. Because I use the primer as a supplement, I have only included a set of brief exercises at the end of each chapter.

Statics Meriam, J. L. (James L.), L. Glenn Kraige, 2008 Over the past 50 years, Meriam, Kraige's *Engineering Mechanics: Statics* has established a highly respected tradition of excellence, a tradition that emphasizes accuracy, rigor, clarity, and applications. Now in a Sixth Edition, this classic text builds on these strengths, adding a comprehensive course management system, Wiley Plus, to the text, including an e-text, homework management, animations of concepts, and additional teaching and learning resources. New sample problems, new homework problems, and updates to content make the book more accessible. The Sixth Edition continues to provide a wide variety of high-quality problems that are known for their accuracy, realism, applications, and variety, motivating students to learn and develop their problem-solving skills. To build necessary visualization and problem-solving skills, the Sixth Edition continues to offer comprehensive coverage of drawing free body diagrams, the most important

skill needed to solve mechanics problems **Engineering Mechanics: Statics, Australian New Zealand Edition** James L. Meriam, L. Glenn Kraige, Jeff N. Bolton, 2019-07-09 A foundation in mechanics principles with integrated engineering design problems Recognized for its accuracy and reliability Engineering Mechanics Statics has provided a solid foundation of mechanics principles for decades The ninth edition helps students develop problem solving skills This text for Australia and New Zealand includes helpful sample and practice problems It guides students in developing visualization and problem solving skills by focusing on the drawing of free body diagrams a key skill for solving mechanics problems *Principles of Engineering Mechanics* Millard F. Beatty, 2005-11-30 Separation of the elements of classical mechanics into kinematics and dynamics is an uncommon tutorial approach but the author uses it to advantage in this two volume set Students gain a mastery of kinematics first a solid foundation for the later study of the free body formulation of the dynamics problem A key objective of these volumes which present a vector treatment of the principles of mechanics is to help the student gain confidence in transforming problems into appropriate mathematical language that may be manipulated to give useful physical conclusions or specific numerical results In the first volume the elements of vector calculus and the matrix algebra are reviewed in appendices Unusual mathematical topics such as singularity functions and some elements of tensor analysis are introduced within the text A logical and systematic building of well known kinematic concepts theorems and formulas illustrated by examples and problems is presented offering insights into both fundamentals and applications Problems amplify the material and pave the way for advanced study of topics in mechanical design analysis advanced kinematics of mechanisms and analytical dynamics mechanical vibrations and controls and continuum mechanics of solids and fluids Volume I of Principles of Engineering Mechanics provides the basis for a stimulating and rewarding one term course for advanced undergraduate and first year graduate students specializing in mechanics engineering science engineering physics applied mathematics materials science and mechanical aerospace and civil engineering Professionals working in related fields of applied mathematics will find it a practical review and a quick reference for questions involving basic kinematics

700 Solved Problems In Vector Mechanics for Engineers: Dynamics Joseph F. Shelley, 1991-04 Suitable for 2nd year college and university engineering students this book provides them with a source of problems with solutions in vector mechanics that covers various aspects of the basic course It offers the comprehensive solved problem reference in the subject It also provides the student with the problem solving drill **Solving Dynamics Problems in Maple by Brian Harper T/a Engineering Mechanics Dynamics 6th Edition by Meriam and Kraige** Brian D. Harper, J. L. Meriam, L. G. Kraige, 2006-12-15 *Engineering Mechanics , Statics* J. L. Meriam, L. G. Kraige, 2001-08-28 Solving Dynamics Problems in MathCad A Supplement to Accompany Engineering Mechanics: Dynamics, 5th Edition by Meriam & Kraige Brian Harper, 2001-11-26 If MathCad is the computer algebra system you need to use for your engineering calculations and graphical output Harper s Solving Dynamics Problems in MathCad is the reference that will be a valuable tutorial for your

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System Dynamics for Mechanical Engineers Matthew Davies,Tony L. Schmitz,2014-11-05 This textbook is ideal for mechanical engineering students preparing to enter the workforce during a

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Essentials of Dynamics and Vibrations John Billingsley, 2025-03-02 This updated second edition brings the complex mathematics of three dimensional dynamics to life with real time simulations making the equations easier to grasp Covering core topics in mechanical engineering such as kinematics dynamics vibration analysis gyroscopes gears and Euler s equations the book offers a clear and engaging approach for students professionals and enthusiasts alike With a focus on practical applications it explains everything from the laws of motion to motors and mechanisms providing a comprehensive understanding of mechanical systems New to this edition is a chapter on Power Energy and Perpetual Motion which reveals intriguing comparisons such as the energy needed to lift water versus the heat required to warm it The final chapter Rocket Science has been expanded to debunk myths about black holes and gravity humorously addressing science fiction misconceptions while proposing exciting space projects

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