

AGES
14+

RC Quadcopter INSTRUCTION MANUAL



2.4GHz

Thank you for purchasing our product. In order to use it correctly and make sure safety, please read the instruction book carefully before using. Please well keep it for your further reference.

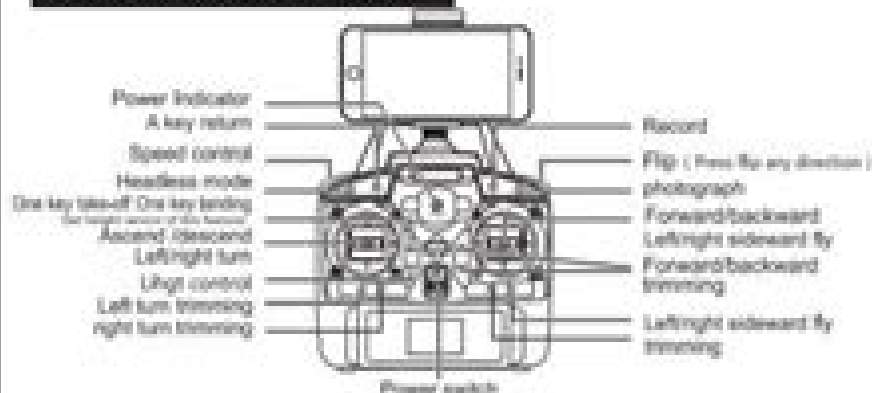
CAUTIONS

1. Any electric component should not be moistened to avoid any other breakdown.
2. If the aircraft is smeared, please do not use any cleanser to clean it as other cleansers will damage the plastic and the synthesis part.
3. Please do not let the aircraft fly away your eye scope during flying.
4. Do not let the children play the aircraft alone.

TECHNICAL PARAMETER

180- Charging time: About 200 minutes
Flying time: About 8 minutes
Remote controlled distance: About 80m

TRANSMITTER INSTRUCTION

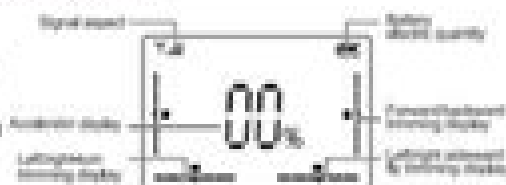


INSTRUCTIONS OF LCD INTERFACE

After installing the batteries, push the remote controller switch to "ON", now the indicator light flashes and signal icon is "1". It means without any signal.

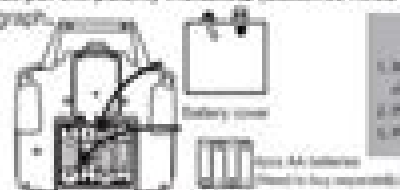
The transmitter will ring twice once pairing succeeds, and the signal icon is "2".

Push the "ascend/descend lever" to the top and then pull it back to the lowest. The transmitter will ring once, power indicator will light. It mean transmitter has started. The LCD interface image is showed as picture.



ASSEMBLING OF THE TRANSMITTER

Open the battery cover on the back of the transmitter and correctly load 4 pcs AA alkaline batteries as per the polarity indicated. (Batteries need to buy separately) as instructions in below graph.



Caution:

1. Make sure the polarity of the battery and battery box should be correct and can't be forced upside down.
2. Please do not mix using the old batteries with the new ones.
3. Please do not mix using batteries with different types.

THE CHARGING INSTRUCTION OF AEROCRAFT BATTERIES

1. Put the charger plug into a socket of AC100V-240V. The charging finishes when the indicator turns green.
2. The power outlet, then insert the plug of the battery charger socket. (note would not be inserted) at the time if you are dissatisfied with a dead battery, the charger light is red and start charging. When charging is complete, the charger light is green. Charging time is 200 minutes.



Rc Quadcopter Manual

Antonio Silvestro



Rc Quadcopter Manual:

Multicopter Design and Control Practice Quan Quan,Xunhua Dai,Shuai Wang,2020-04-17 As the sister book to Introduction to Multicopter Design and Control published by Springer in 2017 this book focuses on using a practical process to help readers to deepen their understanding of multicopter design and control Novel tools with tutorials on multicopters are presented which can help readers move from theory to practice Experiments presented in this book employ 1 The most widely used flight platform multicopters as a flight platform 2 The most widely used flight pilot hardware Pixhawk as a control platform and 3 One of the most widely used programming languages in the field of control engineering MATLAB Simulink as a programming language Based on the current advanced development concept Model Based Design MBD process the three aspects mentioned above are closely linked Each experiment is implemented in MATLAB and Simulink and the numerical simulation test is carried out on a built simulation platform Readers can upload the controller to the Pixhawk autopilot using automatic code generation technology and form a closed loop with a given real time simulator for Hardware In the Loop HIL testing After that the actual flight with the Pixhawk autopilot can be performed This is by far the most complete and clear guide to modern drone fundamentals I've seen It covers every element of these advanced aerial robots and walks through examples and tutorials based on the industry's leading open source software and tools Read this book and you'll be well prepared to work at the leading edge of this exciting new industry Chris Anderson CEO 3DR and Chairman the Linux Foundation's Dronecode Project The development of a multicopter and its applications is very challenging in the robotics area due to the multidomain knowledge involved This book systematically addresses the design simulation and implementation of multicopters with the industrial leading workflow Model Based Design commonly used in the automotive and aero defense industries With this book researchers and engineers can seamlessly apply the concepts workflows and tools in other engineering areas especially robot design and robotics application development Dr Yanliang Zhang Founder of Weston Robot EX product Manager of Robotics System Toolbox at the MathWorks [X-LIPAD Drone Starter Kit PDF](#)

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Concept to Flight Sumit Sharma, 2024-04-30 Learn and apply the principles behind building and flying drones using components like BLDC motors and speed controllers AeroGCS ground software Ardupilot and PX4 open source flight stacks along with examples and best practices Key Features Get to grips with multicopter physics roll pitch and yaw and 3D dynamics for defining a drone's flight Optimize drone performance with powerful propulsion systems such as BLDS motors lipo batteries and ESCs Build a custom survey drone to learn vital aspects of drone assembly configuration testing and maiden flight Purchase of the print or Kindle book includes a free PDF eBook Book Description Unlock opportunities in the growing UAV market where drones are revolutionizing diverse sectors like agriculture surveying and the military This book walks you through the complete drone development life cycle from concept to pilot stage prototyping and ultimately a market ready product with domain specific applications Starting with an introduction to unmanned systems principles of drone flight and its motion in 3D space this book shows you how to design a propulsion system tailored to your drone's needs You'll then get hands on with the entire drone assembly process covering airframe components and wiring Next you'll enhance drone connectivity and navigation with communication devices such as RFD900 Herelink and H 16 Pro GCS and hardware protocols like I2C and UART The book also guides you in using the open source flight software ArduPilot and PX4 along with firmware architecture and PID tuning for advanced control Additionally you'll go learn about AeroGCS Mission Planner and UGCS ground control stations tips for maiden flight and log analysis for optimizing performance while building a custom survey drone with a 60 min endurance 10km range live video feed and photography options By the end of this book you'll be equipped with all you need to build and fly your own drones and UAVs What you will learn Explore the design principles for multicopter flight and its physics of motion Grasp terminologies associated with UAV flight systems Implement power train communication and propulsion concepts in drone design Use IMUs and sensors in flight controllers and protocols like I2C SPI and MAVlink Familiarize yourself with open source drone flight stacks and ground control station software Apply the control law used in multicopter and the basics of PIDs Delve into modes of flying with remote controllers and analysis of flight logs Who this book is for This book is for beginner level drone engineers robotics engineers hardware and design engineers and hobbyists who want to enter the drone industry and enhance their knowledge of the physics mechanics avionics and programming of drones multicopters and UAVs While not a prerequisite a basic understanding of circuits microcontrollers and electronic instruments like multimeter camera and batteries along with fundamental concepts in physics and mathematics will be helpful

The Complete Guide to Drones Extended 2nd Edition Adam Juniper, 2018-05-03 If you think you need a boarding pass to fly you're really missing out Today drones are everywhere From film studios to farms they're in the hands of photographers commercial surveyors and racers alike This fully illustrated book explains how drones developed where they're going and which one you should choose It even includes complete instructions to build both a simple drone and a super fast FPV racer yourself Whether you're flying indoors or out buying or building this book covers

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professionals as well as sector experts who work to develop new drone standards or to identify new drone technology use and commercialization areas at an international level Educates readers on the fundamental properties of an Internet of Drone Things IoDT ecosystem Guides readers to effective network architecture design through experimental modeling and simulations Provides in depth research on the progress made in the domain of UAV networks routing sensing and UAV operation management Offers state of the art IoDT platform enabled application examples

Dasar-Dasar Pengembangan Drone Quadcopter - Jejak Pustaka Ir. Wayan Suparta, Ph.D., Buku ini sebagai panduan bagi pembaca yang ingin mempelajari dan memahami teknologi drone khususnya quadcopter mulai dari komponen komponen utama quadcopter prinsip dasar penerbangan desain dan konstruksi hingga pemrograman dan aplikasi lanjutannya Setiap bab disusun secara sistematis dan dilengkapi dengan ilustrasi serta contoh praktis sehingga pembaca dapat mengikuti setiap langkah dengan mudah Drone quadcopter dengan kemampuan manuvernya yang tinggi dan stabilitas yang baik menjadi salah satu jenis drone yang paling populer dan banyak digunakan

Unmanned Aerial Vehicles Applications: Challenges and Trends Mohamed Abdelkader, Anis Koubaa, 2023-06-29 This is a book that covers different aspects of UAV technology including design and development applications security and communication and legal and regulatory challenges The book is divided into 13 chapters grouped into four parts The first part discusses the design and development of UAVs including ROS customization structured designs and intelligent trajectory tracking The second part explores diverse applications such as search and rescue monitoring distributed parameter systems and leveraging drone technology in accounting The third part focuses on security and communication challenges including security concerns multi UAV systems and communications security The final part delves into the legal and regulatory challenges of integrating UAVs into non segregated airspace The book serves as a valuable resource for researchers practitioners and students in the field of unmanned aerial vehicles providing a comprehensive understanding of UAV technology and its applications

X-LIPAD Drone Starter Kit PDF Module 9 Marc Francis Say, X-Lipad Solutions Inc, 2022-05-24

Model-Based Safety and Assessment Yiannis Papadopoulos, Koorosh Aslansefat, Panagiotis Katsaros, Marco Bozzano, 2019-10-11 This book constitutes the proceedings of the 6th International Symposium on Model Based Safety and Assessment IMBSA 2019 held in Thessaloniki Greece in October 2019 The 24 revised full papers presented were carefully reviewed and selected from 46 initial submissions The papers are organized in topical sections on safety models and languages dependability analysis process safety assessment safety assessment in automotive industry AI in safety assessment

X-LIPAD Drone Starter Kit Presentation Module 7 - First Flight Calvin Ng, Marc Francis Say, X-Lipad Solutions Inc, 2022-05-24

Advances in Engineering Design Rohit Sharma, Ravindra Kannojiya, Naveen Garg, Sachin S. Gautam, 2023-08-19 This volume comprises the select proceedings of the 3rd Biennial International Conference on Future Learning Aspects of Mechanical Engineering FLAME 2022 It aims to provide a comprehensive and broad spectrum picture of the state of the art research and development in engineering design Various

topics covered include engineering system synthesis of mechanism failure analysis solid and structural mechanics contact mechanics multi body dynamics fracture mechanics vibration and acoustics etc This volume will prove a valuable resource for researchers and professionals in the area of mechanical engineering especially engineering design and allied fields

Advanced Robotic Vehicles Programming Julio Alberto Mendoza-Mendoza, Victor Javier Gonzalez-Villela, Gabriel Sepulveda-Cervantes, Mauricio Mendez-Martinez, Humberto Sossa-Azuela, 2020-02-03 Learn how to program robotic vehicles with ardupilot libraries and pixhawk autopilot both of which are open source technologies with a global scope This book is focused on quadcopters but the knowledge is easily extendable to three dimensional vehicles such as drones submarines and rovers Pixhawk and the ardupilot libraries have grown dramatically in popularity due to the fact that the hardware and software offer a real time task scheduler huge data processing capabilities interconnectivity low power consumption and a global developer support This book shows you how take your robotic programming skills to the next level From hardware to software Advanced Robotic Vehicles Programming links theory with practice in the development of unmanned vehicles By the end of this book you ll learn the pixhawk software and ardupilot libraries to develop your own autonomous vehicles What You ll Learn Model and implement elementary controls in any unmanned vehicle Select hardware and software components during the design process of an unmanned vehicle Use other compatible hardware and software development packages Understand popular scientific and technical nomenclature in the field Identify relevant complexities and processes for the operation of an unmanned vehicle Who This Book Is For Undergraduate and graduate students researchers makers hobbyists and those who want to go beyond basic programming of an Arduino for any kind of robotic vehicle **Phaeton divine**

quadcopter Antonio Silvestro, 2020-08-28 The Phaeton divine quadcopter would be used for making synthetic clouds using Uranus InfraRed UltraViolet IR UV laser opening free pathways in the atmosphere before sending the Zeus lightnings with Switched Solid State Tesla Coils SSTC coupled in Laser Induced Plasma Channels LIPC changing the weather purifying the atmosphere and consequently regenerating Nitric Oxides NOx and ozone O3 via the plasma formation in limited and controlled environments suitable for meteorology permaculture and aquaculture applications Furthermore it may be used in biomedical devices as an extensor of the healing range of Hera the lovely resonator for rebirth from Sudden Circulatory Death SCD 48 18 <https://www.amazon.com/dp/B08B4YBD1Q> for awakening MI SCD in need of pressurizing and breath taking complex wave radiation pulsing back the suffering heart It is to note that it could be remotely controlled not just by regular transmitters and smartphone APP but also via brain interfaces just thinking about what it needs to accomplish

Model-Based Safety and Assessment Marco Bozzano, Yiannis Papadopoulos, 2017-09-01 This book constitutes the proceedings of the 5th International Symposium on Model Based Safety and Assessment IMBSA 2017 held in Trento Italy in September 2017 The 17 revised full papers presented were carefully reviewed and selected from 29 initial submissions The papers are organized in topical sections on safety process safety models and languages fault detection and propagation

safety assessment in the automotive domain and case studies *Applications of Computational Methods in Manufacturing and Product Design* B. B. V. L. Deepak,D.R.K. Parhi,B.B. Biswal,Pankaj C. Jena,2022-05-04 This book presents the select proceedings of the conference of Innovative Product Design and Intelligent Manufacturing System IPDIMS 2020 held at the National Institute of Technology Rourkela India The book addresses latest methods and advanced tools from different areas of design and manufacturing technology The main topics covered include computational methods for robotics mechatronics and human computer interaction computer aided design manufacturing and engineering aesthetics ergonomics and UX UI design smart manufacturing and expert systems The contents of this book will be useful for researchers as well as professionals working in the areas of industrial design mechatronics robotics and automation **Advanced Mechanical Science and Technology for the Industrial Revolution 4.0** Ligang Yao,Shuncong Zhong,Hisao Kikuta,Jih-Gau Juang,Masakazu Anpo,2017-10-30 This book includes more than 30 papers from the first FZU OPU NTOU Joint Symposium on Advanced Mechanical Science and Technology for the Industrial Revolution 4 0 held at Fuzhou University China in December 2016 The symposium was organized by Fuzhou University FZU Osaka Prefecture University OPU and National Taiwan Ocean University NTOU The authors include several professors from universities in China Japan and Taiwan as well as four distinguished invited professors from Canada Korea Japan and Taiwan The book covers all important aspects related to the 4 0 industrial revolution robotics and mechatronics sensors measurements and instrumentation mechanical dynamics and controls mechanical design vehicle systems and technologies fluid mechanics monitoring and diagnosis prognosis and health management advanced signal processing and big data all of which are subjects with great potential in the field of mechanical engineering

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web mar 21 2019 where the foam on mine was missing so i blocked it off atm so nothing can get into the port and block the solenoid i did think about running a vac hose to the air filter box and get a brass fitting and connect it on the filtered side of

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web mar 29 2021 i haven t put it all back together yet because i broke one of the vacuum hoses that runs the cruise control and can t find one there is a diaphragm on the passenger side of the car that operates the cruise control and it has a couple of hoses running to it

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web nov 15 2018 vl berlina turbo 1987 nov 15 2018 1 does anyone have a diagram on how to run the vacuum hoses from the plenum and reservoir in the engine bay through to the hvac controls sorry if this sounds very basic but we ve just done a

rebuild and the new shell didn't come with the hoses but does have the reservoir many thanks

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web oct 5 2017 i cover the hose opening with my finger raises engine revs and i can feel suction hissing noise stops as mentioned its in the shape of a 90 degree angle about 30mm long in all has it been cut short if so where would it connect to unfortunately my gregorys does not have a vacuum hose diagram

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web vacuum hose diagram vt commodore v6 supercharged 3 3 command aetc the air force reserve command afrc air national guard ang and headquarters air force compiled inputs from the field and rebuilt the tongue and quill to meet the needs of today's airmen the team put many hours into this effort over a span of almost two

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web jun 12 2016 does anyone know where i can find a diagram of all the vacuum hoses on a vx v6 ecotec i tried looking on google images to no avail i want to have a look at all my vacuum hoses i know where the majority of them are located but just want to make sure i

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